

Kawasaki Robotics

K-Virtual

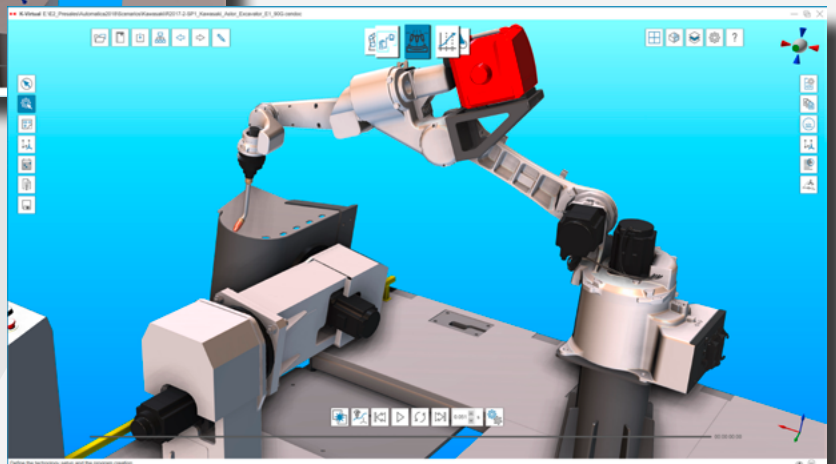


Kawasaki Robotics K-Virtual

Setting up Automation the Easy Way

K-Virtual: Focus on Efficiency

The complexity of manufacturing processes and solutions is increasing daily - it is our goal to make them simpler and to allow you to focus on your core tasks. Based on CENIT's proven FASTSUITE technology K-Virtual enables agile development, programming and optimization of complex robot applications via an intuitive platform and a digital twin of your system.



Ready for Industry 4.0

Industry 4.0 requires new approaches and concepts. Virtual factories and plant models must be an accurate representation of real production systems in every respect. With K-Virtual we offer you the optimal tool for planning individual automation. K-Virtual is the new software solution for efficient plant engineering, practical robot simulation and convenient offline programming of Kawasaki robots.

Use the Full Potential of Your Kawasaki Robots

K-Virtual will be available in several editions - from Basic to Expert - and optimized for various applications like arc welding. Companies are thus able to fully exploit the full performance capability of their Kawasaki robots within individual automation solutions - from initial installation to reprogramming and plant re-engineering.



Make Your Automation Ready for the Future

Demanding applications are difficult to implement in the required process quality and efficiency using manual programming. Simulation-based solutions therefore play an increasingly important role in the implementation of new plant concepts or manufacturing processes. With K-Virtual as an intuitive and agile 3D simulation platform, Kawasaki Robotics offers its customers the optimal tool for the future-proof planning of their automation processes - easier than ever before.

K-Virtual: Extremely convenient and agile

Easily and intuitively create complex programs.
Improve the quality of your automated processes.
Save time and money.

Change Forward: Kawasaki Robotics



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